



### Assignment no 03: Chapter 3

**Note:** You can check the exercises after the book Chapter.

In our assignment, we are using the first edition of “Signals and Systems: A MATLAB Integrated Approach” By Oktay Alkin.

### Problems

**3.1.** A number of discrete-time systems are specified below in terms of their input-output relationships. For each case **determine** if the system is linear and/or time-invariant.

- a.  $y[n] = x[n] u[n]$
- c.  $y[n] = 3 x[n] + 5 u[n]$
- e.  $y[n] = \cos(0.2\pi n) x[n]$
- f.  $y[n] = x[n] + 3 x[n - 1]$

**3.2.** Determine if the system is linear or not.

b. 
$$y[n] = \sum_{k=0}^n x[k]$$

**3.3.** Consider the cascade combination of two systems shown in Fig. P.3.3(a).



**Figure P. 3.3**

**a.** Let the input-output relationships of the two subsystems be given as

$$\text{Sys}_1 \{x[n]\} = 3 x[n] \quad \text{and} \quad \text{Sys}_2 \{w[n]\} = w[n - 2]$$

**Write** the relationship between  $x[n]$  and  $y[n]$ .

**b.** Let the order of the two subsystems be changed as shown in Fig. P.3.3(b).

**Write** the relationship between  $x[n]$  and  $\bar{y}[n]$ .

**Does** changing the order of two subsystems change the overall input-output relationship of the system?



3.5. The response of a linear and time-invariant system to the input signal  $x[n] = \delta[n]$  is given by

$$\text{Sys} \{ \delta[n] \} = \left\{ \underset{\substack{\uparrow \\ n=0}}{2}, 1, -1 \right\}$$

**Determine** the response of the system to the following input signals:

- $x[n] = \delta[n] + \delta[n - 1]$
- $x[n] = \delta[n] - 2\delta[n - 1] + \delta[n - 2]$
- $x[n] = u[n] - u[n - 5]$

3.7. The discrete-time signal is used as input to a length-2 moving average filter.

$$x[n] = \left\{ \underset{\substack{\uparrow \\ n=0}}{1.7}, 2.3, 3.1, 3.3, 3.7, 2.9, 2.2, 1.4, 0.6, -0.2, 0.4 \right\}$$

**Determine** the response  $y[n]$  for  $n = 0, \dots, 9$ . Use  $x[-1] = 0$ .

3.25. For each system described below, **determine** whether the system is causal and/or stable.

- $y[n] = \text{Sys} \{ x[n] \} = \sum_{k=-\infty}^n x[k]$
- $y[n] = \text{Sys} \{ x[n] \} = \sum_{k=0}^n x[k] \quad \text{for } n \geq 0$
- $y[n] = \text{Sys} \{ x[n] \} = \sum_{k=n-10}^{n+10} x[k]$

## Examples

**Example 3.19:** A discrete-time system is described through the impulse response

$$h[n] = \left\{ \underset{\substack{\uparrow \\ n=0}}{4}, 3, 2, 1 \right\}$$

Use the convolution operation to find the response of the system to the input signal

$$x[n] = \left\{ \underset{\substack{\uparrow \\ n=0}}{-3}, 7, 4 \right\}$$